

# STIR: A Smart and Trustworthy IoT System Interconnecting Legacy IR Devices

Zhen Ling<sup>✉</sup>, Chao Gao, Chuta Sano, Chukpozohn Toe, Zupei Li, and Xinwen Fu<sup>✉</sup>

**Abstract**—Legacy-infrared (IR) devices are pervasively used. They are often controlled by IR remotes and cannot be controlled over the Internet. A trustworthy and cost-effective smart IR system that is able to change an IR controllable device into a smart Internet of Things (IoT) device and interconnect them for smart city/home applications is offered in this article. First, a printed circuit board (PCB) consisting of an IR receiver and multiple IR transmitters side by side which are capable of transmitting about 20 m indoors is designed and implemented. This IR transceiver board is the first of its kind. Second, the IR transceiver can be linked up with a Raspberry Pi, for which we develop two software tools, recording and replaying any IR signals so as to put the corresponding IR device in control. Third, a smartphone can be connected to the Pi by means of a message queuing telemetry transport (MQTT) cloud server so that the commands can be sent by the smartphone to the legacy IR device over the Internet. We have also identified the deficiency of TLS mutual authentication implemented by the popular MQTT open-source package Mosquitto for a trustworthy IoT system and patched the system. We analyze the factors that affect the IR signal transmission distance, discuss the security concerns of our IR transceiver, and illustrate the scenarios for attacks. For instance, TV can be turned off remotely by a drone equipped with the transceiver.

**Index Terms**—Drone, infrared (IR), Internet of Things (IoT), smart home.

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Zhen Ling is with the School of Computer Science and Engineering,



and 1.125 ms for 1 and 0, respectively. An NEC message starts with a header of 9-ms pulse and 4.5-ms space, followed by a 16-bit address (8-bit address and 8-bit logical inverse of the address) and a 16-bit command (8-bit command and 8-bit logical inverse of the command). An additional 562.5- $\mu$ s pulse indicates the end of transmission. In case of a key being continuously pressed, the command is sent out once and a repeat code is then sent every 108 ms. The repeat code is composed of a 9-ms pulse, a 2.25-ms space and, finally, a 562.5- $\mu$ s pulse to mark the end of the message transmission [11].

### B. Raspberry Pi

A Raspberry Pi is a lightweight computer that runs on an ARM CPU. A Pi may run various operating systems. In this article, all the Raspberry Pis use Raspbian, a Debian-based Linux OS system. In our experiments, Raspberry Pi 3 and Zero W were adopted despite other similar devices.

### C. MQTT

MQTT [5] is a popular lightweight protocol to implement IoT communications. MQTT is a topic-based, publisher, and subscriber messaging system. A message contains a message topic and message payload. The topic is a unique string that serves as the identifier for a type of message. A publisher is any client that sends messages. A subscriber is any client that listens for incoming messages of a particular topic. The term client or node refers to any system/device that connects to a broker and publishes and/or subscribes to topics while the broker relays the messages between clients.

Mosquitto [6], an open-source implementation of MQTT, supports MQTT over TLS [12]. Mosquitto provides a broker along with publish and subscribe tools. Paho-mqtt [13] is a library in Python for MQTT and provides APIs to subscribe and publish to topics.

## III. SMART AND TRUSTWORTHY IR SYSTEM

In this section, the architecture of the smart IR system is introduced. Then, the hardware and software of the smart IR transceiver are presented in detail, followed by the explanation of the smart IR controller and trustworthy cloud server which are aimed at controlling the legacy IR devices from anywhere over the Internet. Finally, factors that affect the IR transmission range are discussed.

### A. Architecture of Smart IR System

Fig. 2 shows the smart IR system architecture. It is made up of four components: 1) a legacy IR device; 2) a smart IR transceiver; 3) a cloud server/broker; and 4) a smart IR controller. The legacy IR device can be any consumer IR device. The smart IR transceiver is able to control the legacy device by recording IR signals of the legacy IR remote and replaying them. The smart IR transceiver is connected to the cloud server via the Internet. The smart IR controller can be a smartphone with our t6cp18.6(can)h them.cloud publer

module, and a power protection circuit. A Pi is connected to the transceiver's I/O interface, which includes four GPIO pins, J-1, J-2, 3.3 V, and GND. The transceiver receives power from the 3.3-V pin and the ground is connected to a ground pin on the Raspberry Pi. The Raspberry Pi sends signals through the GPIO pin (J-1) to the transceiver board, which turns the IR LEDs/transmitters on or off. The receiver module of the transceiver board records the signals from a legacy IR remote and sends it to the Pi through the GPIO pin (J-2). The receiver module uses a 38-kHz IR module of 940-nm peak wavelength.

The transmitter circuit of the IR transceiver board is optimized. First, the power supply is routed through the power protection circuit consisting of a 100- $\mu$ F capacitor (C2) and a 0.1- $\mu$ F capacitor (C1). Since the IR signal is fired in short bursts, C2 can store charge to increase the stability in case the Raspberry Pi fails to transmit steady current to the LED. C1 removes small electric noise and protects the whole circuit.

Second, four IR LEDs (D1~D4) with wavelength of 940 nm are placed in parallel to maximize the coverage of the IR signal. In Section V-C, we will evaluate the impact of the combination of LEDs with wide coverage and narrow coverage on the transmission range.

GPIO pin commands pass through the PNP (Q1) transistor to each IR LED, which is connected to a driver transistor (NPN transistor). The transistor Q1 is used as a buffer to amplify the weak signal from the GPIO pin and push the required amount of current into the bases of the NPN driver transistors (Q2 ~ Q5). Each NPN transistor is capable of amplifying the power of the command signal. To protect the circuit, they are designed to turn off the LEDs if the current is greater than 100 mA. These transistors increase the intensity of the IR light, leading to a higher range of IR transmission.

2) *Software of Smart IR Transceiver*: Software of the smart IR transceiver runs on the Raspberry Pi and has two parts, one for communication with the IR hardware transceiver board and the other for communication with the cloud server to receive commands from the smart IR controller. The smart IR transceiver software can handle intricacies of low level arising from the IR communication.

PiGPIO library written in C++ is adopted by the receiver module software. It keeps account of the duration between low and high inputs received from the receiver in raw format, in which positive numbers represent the on duration of LED in microseconds, while the negative ones represent the off duration in microseconds. The most important function used in the receiver module software is *gpioSetAlertFunc()*. It records the GPIO state changes (from high to low or from low to high) and timestamps it in microseconds. This function samples the status of the GPIO pin and records the status (high or low) and timestamp after the status is changed. The samples are captured by the direct memory access (DMA) hardware and written to a large cyclic buffer in the memory. The user is able to access this buffer every millisecond and the default buffer size is 120 ms of samples. The default sampling rate is 200 kHz. Recall that the IR signal bandwidth is 38 kHz. According to the Nyquist–Shannon sampling theorem [14], a signal waveform can be recovered when the sampling frequency is greater than or equal to twice the signal

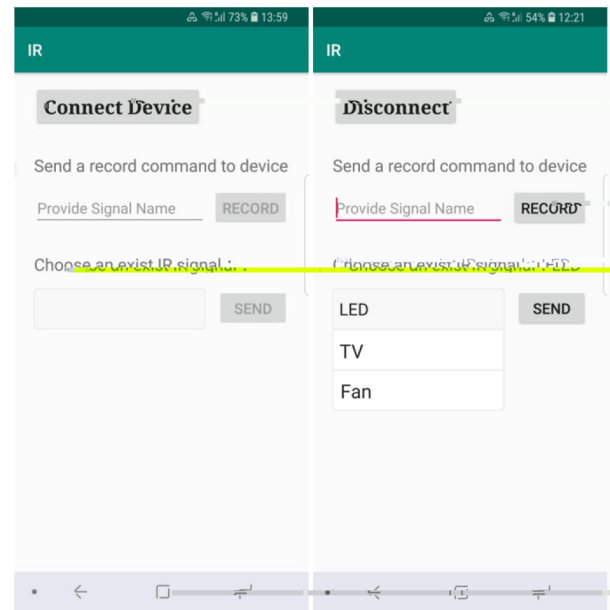


Fig. 5. Android application.

frequency. Therefore, we can correctly record and replay the recorded signal using the IR transceiver board.

The STIR app installed on the smart IR controller allows the user to name the recording, which is saved to “ircodes.txt” in the Raspberry Pi by default. Each recording has two lines: the first one is “name: <name>,” namely, the name entered from the STIR app on the smart IR controller. The second is a list of integers delimited by spaces to represent the recorded IR signal.

We implement the transmitter software in C++. The transmitter software uses the PiGPIO library to have the nanosecond accuracy for the GPIO control. This is necessary to correctly replay the IR signals. The transmitter software communicates with the smart IR controller to obtain the name of the IR signal to be replayed. The transmitter software then attempts to read the matching line with the same name from the *ircodes.txt* and replays the previously recorded signal. Our transmitter software has implemented the previously mentioned raw format scheme, pulse-distance, pulse-length, and bi-phase encoding, and the NEC and RC-5 protocols.

Using the IR transceiver hardware and software, we can now connect our IR transceiver hardware board to a Raspberry Pi as a smart IR transceiver and control an IR device by recording and replaying its IR signals. Since a Raspberry Pi has the Internet capability, we can connect the Raspberry Pi to the Internet and control the IR device over the Internet through a smart IR controller.

### C. Smart IR Controller

We implement the STIR Android app that remotely controls the IR transceiver circuit board connected to the Raspberry Pi through the MQTT protocol. Fig. 5 shows the Android app, which can connect to the smart IR transceiver through the cloud server. We can use the app to send a command to the IR transceiver circuit board so as to record the IR signals

from any legacy IR controllers. Additionally, we can choose any recorded IR signal (such as TV, LED, and fan shown in Fig. 5) and send it to the smart transceiver that can transmit the corresponding IR signals to the IR device.

#### D. Trustworthy Cloud Server

Mosquitto is chosen as the message broker for the MQTT protocol which has been expounded in Section II-C. Our Mosquitto cloud server is built on an Amazon EC2 virtual machine backed with the SSL/TLS transfer security. Both the IR transceiver and smart IR controller can be connected to this server. The smart IR controller sends a control command to a specific topic, to which the smart IR transceiver subscribes. Upon receiving the control command, the smart IR transceiver can send the signal via its IR transceiver board to the corresponding IR device. A Mosquitto broker is installed on the Pi of the smart IR transceiver so that the smart controller and IR transceiver can locally communicate through the MQTT broker on the Pi. The Raspberry Pi of the smart IR transceiver can be configured to be a wireless access point (AP), denoted as *Rasp-AP* so that the smart IR controller can connect to Rasp-AP and send a control command to the broker on the Pi. The Pi then commands the transceiver board and sends the IR signal to the corresponding IR device.

We found that the implementation of the current mutual authentication by Mosquitto, which supports SSL/TLS, is flawed to some extent. For mutual authentication and connection encryption, the configuration of the Mosquitto server should contain the certificate of the certificate authority (CA), the server certificate issued by the CA and the server private key. Thus, a device which is connected to the Mosquitto server should have the CA certificate, the client private key, as well as the client certificate signed by the CA. As for the server authentication, the CA certificate is used by the device to validate the server certificate and check if the subject/domain name in the server certificate matches the domain name the client intends to connect to. However, the Mosquitto's client certificate-based authentication strategy has security pitfalls. The Mosquitto server only checks if the client certificate is signed by the trusted CA, without verification of the particular identity of the client who is allowed to use the server or not. Therefore, if an attacker obtains any valid client certificate generated by the CA, he/she can spoof the device and may communicate with the server in a malicious way, for example, sending fake messages.

With the purpose of addressing the flaw of Mosquitto's certificate-based client authentication, the Mosquitto source code is revised and the hash of the client certificate of a device along with the client certificate ID is stored in a database at the Mosquitto server. In *src/net.c* of the Mosquitto, we add a new function called *client\_certificate\_verify()*. After the validation of the client certificate by Mosquitto, the new function searches the ID of the certificate sent by the connecting device in the server database. If the certificate ID does not exist, the client is disconnected. If yes, the new function hashes the client certificate provided by the connected device and compares it to the hash value associated with the client certificate

ID in the server database. If they are the same, the client is allowed to connect to the server. Otherwise, the server is disconnected from the client.

#### E. IR Transmission Range

A legacy IR receiver is typically packaged by a combination of a photodiode and an integrated circuit, which can receive an IR signal and decode the received IR signal. There are two common IR wavelengths, 850 and 940 nm for IR LEDs. With more power and long transmission range, the 850-nm LED produces a slight red glow, visible to human eyes. With a short transmission range and lower power, 940-nm LED is not visible to human eyes, but it is cheaper and commonly used to control small consumer electronics.

The transmission range of the IR signal is mainly up to the radiant intensity of the IR emitter/transmitter together with the irradiance of the legacy IR receiver [15]. The maximum transmission range  $d_{\max}$  of a smart IR control system can be calculated with the use of the following equation [15]:

$$d_{\max} = \sqrt{\frac{I}{E_{\min}}} \quad (1)$$

where  $I$  is the radiant intensity of the IR emitter and  $E_{\min}$  is the minimum irradiance of the legacy IR receiver.

The radiant intensity of an IR LED mainly rests upon the current flow through the LED. The higher the current is, the greater the intensity is. Nonetheless, each type of LED has its limit on the maximum current it can pass. The radiant intensity is also pertinent to the viewing angle of the IR LED. The viewing angle  $\theta$  is defined as the angle from which LED light spreads. Outside of  $\theta$ , the intensity falls under 50% of its maximum brightness [16]. If multiple LEDs are placed in parallel, the radiation intensity of the overlapping portion of the viewing angle can be enhanced by superposition. This is the reason for our use of multiple IR LEDs to increase the transceiver's transmission range.

Except for the above-mentioned factors, there are other factors that cast an influence on the transmission range. The reflectivity of the surrounding walls, the optical transmittance of the window in front of the receiver, and external noise, such as lights from sun or light bulbs, all influence the coverage and range of the signal. Therefore, noise suppression capabilities of legacy IR receivers can affect the IR signal receiving distance too.

### IV. SECURITY IMPLICATIONS

In this section, a discussion on the threats from the IR transceiver that could be employed to attack IR controllable devices, as exemplified by TVs, air conditioners, fans, and thermal control units, is given, since the relevant attacks may result in damages from daily inconveniences to property loss.

#### A. Replay Attack

Since consumer IR devices are lack of regular encryption of their IR codes, security concerns can arise. For instance, TVBGone [17] can turn on/off TVs by replaying known codes.

It takes about two minutes for TVBGone to replay all the codes, and this is definitely a congruent time frame for the attacks of any TV [17]. As for our IR transceiver, it is able to keep account of any IR codes from IR controllable devices and run these codes accordingly. Under the control of a Raspberry Pi, this IR transceiver is prone to being customized to attack any device that is controlled by IR.

### B. Brute-Force Attack

The brute-force attack is capable of traversing all possible bits of a given protocol and attacking any unknown device with the use of that protocol. In terms of the NEC protocol, a potential command is built on the unique address and command bits. Since 8 bits are included in the address and command, respectively, a total of  $2^{16} = 65\,536$  possible combinations come into shape. According to our experiments, it takes 67.5 ms for each command to be sent. However, with a total of 65 536 distinct NEC messages, the time duration for the worst-case scenario is just beyond one hour. In order to give an illustration of the brute-force attack, the NEC brute-force attack is deployed against a remote-controlled lightstrip [18]. Its objective is to turn on/off the lightstrip. With the employment of this method, the light can be hacked in milliseconds. In the attack, 0x00 and 0x00 were set to be the starting bits for address and command, respectively. As a matter of fact, address 0x00 and command 0x02 are used by the lightstrip.

In total, 11 bits are adopted by RC-5, with 5-bit addresses and 6-bit commands. Therefore,  $2^{11}$  different messages can be found in the RC-5 protocol. 24.9 ms is needed for sending an RC-5 command signal. The RC-5 brute-force attack can be finished within 51 s.

### C. Drone Attack

There remains one difficulty in attacking IR devices, that is, the IR transceiver—the doer of this attack—needs to approach the target IR devices as close as possible. In order to circumvent accessibility-related issues, the Raspberry Pi and IR transceiver could be placed on a drone. Since the former is Internet-based, the IR transceiver can be controlled by people from anywhere.

The drone attack in our experiment is performed with a DJI Phantom 2 [19]. With the purpose of minimizing weight and maximizing flight duration, the on-board camera was removed. Powered by a mini battery [20], a Raspberry Pi 3 was mounted onto the drone together with an early version of our IR transceiver. In accordance with the experiment, it has been found that the TV inside the second-floor conference room can be turned on and off by the drone which flew outside.

### D. Securing IR Communication

For the defense against the above-mentioned attacks, one may want to encrypt the IR communication. The major issue of encrypting IR messages is the overhead. It can be seen from the discussion above that an IR message is often fewer than two bytes. Using encryption or the message integrity code will add tens of extra bytes to the IR message. This may affect the

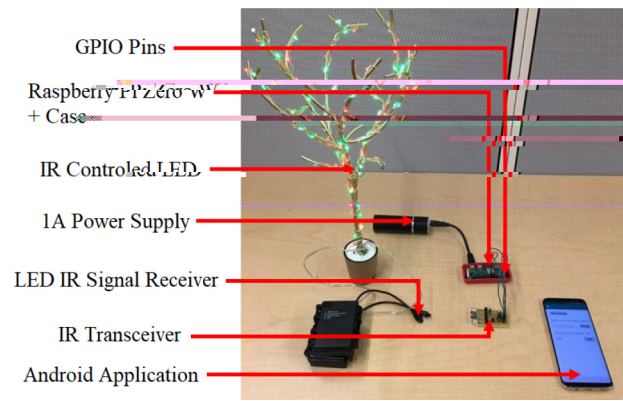


Fig. 6. IR device setup.

transmission delay of the IR message and may be a reason we do not see much work on encrypting IR communication. The advance of MCUs actually makes encrypting the IR communication possible [21] with hardware crypto acceleration. A capable MCU can be used at the receiver side of IR communication for this purpose. However, for high-value assets, a more capable communicating venue, such as WiFi, may be used rather than IR.

## V. EVALUATION

In this section, a prototype of STIR, the smart and trustworthy IoT system connecting legacy IR devices to the Internet is introduced first. Then, the cost of the prototype, evaluation of its performance, and the attacks against IR communication are discussed. Finally, limitations and potential improvements to STIR are given for further discussions.

### A. Prototype of STIR

Fig. 6 shows the prototype of STIR and a test setup. On the left is an IR controlled LED strip which is wrapped around a tree-like artifact together with its IR receiver. On the right is the IR transceiver circuit board connected to the Raspberry Pi Zero W [22] through GPIO pins. From bottom to top, the four connected pins found on the IR transceiver are linked up with GPIO 22 (sender pin), GPIO 23 (receiver pin), a 3.3-V power pin, and a ground pin of Raspb.2(m0415.pin,Z3 spin,respectively

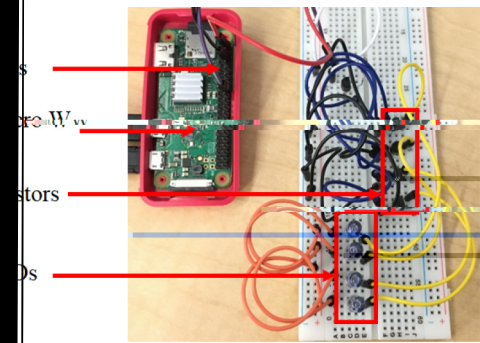


Fig. 7. Radiation intensity test setup.

TABLE II

The experiment is performed 30 times, the average delay is 175 ms, and the estimated density function is shown in Fig. 7. We also survey 30 people to study tolerable delay. We artificially add delay at the smartphone sending a command to turn on the lightstrip and ask the subject if it is tolerable. The survey shows that the delay of our smart IR system can be acceptable to 99% ( $1 \times 0.85 + 0.93 \times 0.15$ ) of people.

### B. Cost

Owing to the variations of cost arising in PCB printing (such as the costly construction of one module), the cost of the IR transceiver module is approaching \$8.00. Our experiments were performed on the Raspberry Pi Zero W, costing only \$10.00. As a result, the direct cost of the whole setup can be minimized to approximately below \$18.00 with a Raspberry Pi Zero W.

### C. Transmission Range

As previously mentioned, two different types of IR LEDs are adopted in our experiments, i.e., wide IR LEDs and narrow IR LEDs, with 940-nm wavelength to evaluate the effect of the radiation intensity and viewing angle of the emitter on the transmission range. The wide IR LED has maximum 45 mW/Sr (milliwatt per steradian [23]) radiant intensity with a 40° viewing angle and the narrow IR LED has maximum 80 mW/Sr radiant intensity with a 20-degree viewing angle. We build the IR transceiver circuit on a breadboard as shown in Fig. 8 and evaluate the IR LED maximum transmission distance in a large dim empty room. On the left of the figure is the Raspberry Pi Zero W [22], which is used to connect and control the IR transceiver circuit through the GPIO pins.

Table II shows the IR LED maximum transmission distance for different types of LEDs and power supply. The maximum transmission distance is the longest distance at which our transceiver can operate the lightstrip module. For both types of LEDs, more numbers of LEDs lead to better range. It has been found that with the use of the same type of LED, the LED with a 5-V power supply has

TABLE III  
TRANSMISSION DISTANCE IN DIFFERENT ENVIRONMENTS

Situation	3.3V	5V
Inside, large room with no pockets	20.18m	22.93m
Outside, in shade, through a window, receiver inside a room	8.78m	10.58m
Outside, receiver facing the sun	0.60m	0.75m
Outside, receiver facing away from the sun	3.07m	3.21m
Outside, in shade	10.71m	13.21m

and consists of a PIN photodiode, a preamplifier, and an IR filter. The IR sensitive area of the IR photodiode is denoted as the IR-photosensitive surface of the IR receiver. The signal transmission range over 3.3 and 5-V power supply is thus evaluated.

Table III presents the transmission range of the IR transceiver module used in five different scenarios. In the first case (*Inside, large room with no pockets*), both the IR transceiver and receiver are placed indoors. In the second case (*Outside, in shade, through a window, receiver inside a room*), the IR transceiver is put outdoors under the shadow of the building and controls the receiver (which was located indoors) through the window. As for the three scenarios, both the IR transceiver and receiver are placed outdoors. In the third case (*Outside, receiver facing the sun*), the IR transceiver is directly exposed to sunlight, and the IR-photosensitive surface of the receiver faces the sunlight. In the fourth case (*Outside, receiver facing away from the sun*), the IR transceiver is directly exposed to sunlight, but the receiver's IR-photosensitive surface faces away from the sunlight. In the fifth case (*Outside, in shade*), both the IR transceiver and receiver are placed under



at the core [4]. Our software, with remarkable usability, is a significant advancement of the LIRC. IrSlinger [25] is a simple IR sender program that uses the PiGPIO daemon for precise timing on Raspberry Pi.

Toolkits have also been developed to play with IR signals. TVBGone, a device of light weight, is capable of turning on/off TV [17]. Governed by an IC chip, it hardcodes possible TV power toggle signals in the IC chip. Its precise timing is effected and gained via a ceramic resonator. Arduino Universal Remote [26], with the use of a breadboard, can only keep account of and playback one signal without security and remote control over the Internet. IR photo transistor, rather than IR transceiver, is employed to record signals by IRRememberizer [27] to keep a record of signals from 30 to 60 kHz. However, IRRememberizer suffers from less reliability and declining range because the photo resistor is of high likelihood to be affected by interference from exterior IR sources [27]. Based on this consideration, a 38-kHz IR receiver module with high stability and range in the process

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