Advanced Data Structures

Medians and Order Statistics



- The *i*th *order statistic* in a set of *n* elements is the *i*th smallest element
- The *minimum* is thus the 1st order statistic
- The *ma imum* is the *n*th order statistic
- The *median* is the n/2 order statistic
 - If n is even, there are 2 medians
- *Ho* can e calculate order statistics?
- What is the running time?

Order Statistics

Ho man comparisons are needed to find the minimum element in a set? The ma imum?
Can e find the minimum and ma imum ith less than t ice the cost?

- Yes:
 - Walk through elements by pairs
 - Compare each element in pair to the other
 - Compare the largest to maximum, smallest to minimum

Total cost: 3 comparisons per 2 elements = O(3n /2)

Finding Order Statistics: The Selection Problem

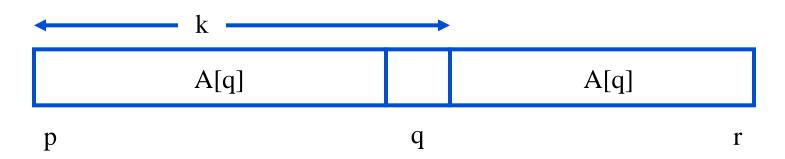
- A more interesting problem is *selection*: finding the *i*th smallest element of a set
- We will show:
 - A practical randomized algorithm with O(n) expected running time
 - A cool algorithm of theoretical interest only with O(n) worst-case running time

- Key idea: use partition() from quicksort
 - But, only need to examine one subarray
 - This savings shows up in running time: O(n)
 - q = RandomizedPartition(A, p, r)

A[q]		A[q]	
р	q		r

RandomizedSelect(A, p, r, i)

return RandomizedSelect(A, q+1, r, i-k);



- Analyzing RandomizedSelect()
 - Worst case: partition always 0:n-1
 - T(n) = T(n-1) + O(n) = ???
 - $= O(n^2)$ (arithmetic series)
 - No better than sorting!
 - Best" case: suppose a 9:1 partition
 - T(n) = T(9n/10) + O(n) = ???
 - = O(n) (Master Theorem, case 3)
 - Better than sorting!
 - What if this had been a 99:1 split?

• Average case

For upper bound, assume *i*

• Assume T(n) cn for sufficiently large c:

$$T(n) \leq -\frac{1}{n}\sum_{k=n/2}^{n-1}T(k) + \Theta(n)$$

$$\leq -\frac{1}{n}\sum_{k=n/2}^{n-1}ck + \Theta(n)$$

$$W$$
?
$$= -\frac{c}{n}\left(\sum_{k=1}^{n-1}k - \sum_{k=1}^{n/2}k\right) + \Theta(n)$$
"S
"
$$= -\frac{c}{n}\left(\frac{1}{n}(n-1)n - \frac{1}{n}\left(\frac{n}{n}-1\right) + \Theta(n)\right)$$

$$W$$
?
$$= c(n-1) - \frac{c}{n}\left(\frac{n}{n}-1\right) + \Theta(n)$$

$$W$$
?

• Assume T(n) cn for sufficiently large c: $T(n) \leq c(n-1) - \frac{c}{2}\left(\frac{n}{2} - 1\right) + \Theta(n)$ T $= cn - c - \frac{cn}{4} + \frac{c}{2} + \Theta(n)$ M $= cn - \frac{cn}{\Lambda} - \frac{c}{2} + \Theta(n)$ S /2 $= cn - \left(\frac{cn}{4} + \frac{c}{2} - \Theta(n)\right)$ R \leq cn (if cisbig enough) W

- Randomized algorithm works well in practice
- What follows is a worst-case linear time algorithm, really of theoretical interest only
- Basic idea:
 - Generate a good partitioning element
 - Call this element

• The algorithm in words:

- 1. Divide *n* elements into groups of 5
- 2. Find median of each group (*Ho* ? *Ho long*?)
- 3. Use Select() recursively to find median of the $\lfloor n/5 \rfloor$ medians
- 4. Partition the *n* elements around . Let k = rank()
- 5. **if** (i == k) **then** return x
 - if (i < k) then use Select() recursively to find ith smallest
 element in first partition</pre>
 - else (i > k) use Select() recursively to find (i-k)th smallest
 element in last partition

- Ho man of the 5-element medians are ? • At least 1/2 of the medians = $\left| \frac{n}{5} \right| / 2 = \frac{n}{10}$ • Ho man elements are 2 At least 3 n/10 elements • For large n, 3 | n/10 | n/4 (Ho large?) • So at least *n*/4 elements
- Similarly: at least *n*/4 elements

n

- Thus after partitioning around , step 5 will call Select() on at most 3*n*/4 elements
- The recurrence is therefore: $T(n) \quad T(|n/5|) \quad T(3n/4) \quad (n)$ T(n/5) T(3n/4) (n)cn/5 3cn/4 $\Theta(n)$ $= 19cn/20 + \Theta(n)$ $= cn - (cn/20 - \Theta(n))$ $\leq cn$ if c is big enough

• Intuitively:

Work at each level is a constant fraction (19/20) smaller

• Geometric progression!

Thus the O(n) work at the root dominates

Linear-Time Median Selection

- Given a "black box" O(n) median algorithm, what can we do?
 - *i*th order statistic:
 - Find median
 - Partition input around
 - if (i (n+1)/2) recursively find *i*th element of first half
 - else find (i (n+1)/2)th element in second half
 - T(n) = T(n/2) + O(n) = O(n)

Linear-Time Median Selection

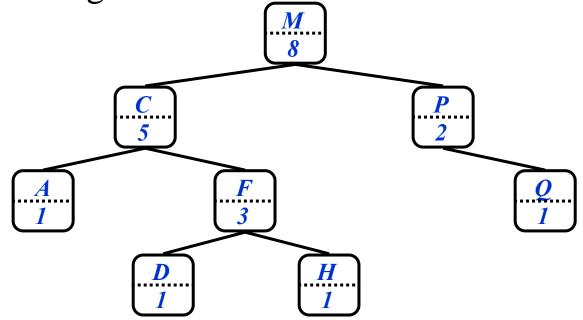
- Worst-case O(n lg n) quicksort
 - Find median and partition around it
 - Recursively quicksort two halves
 - $T(n) = 2T(n/2) + O(n) = O(n \lg n)$

Dynamic Order Statistics

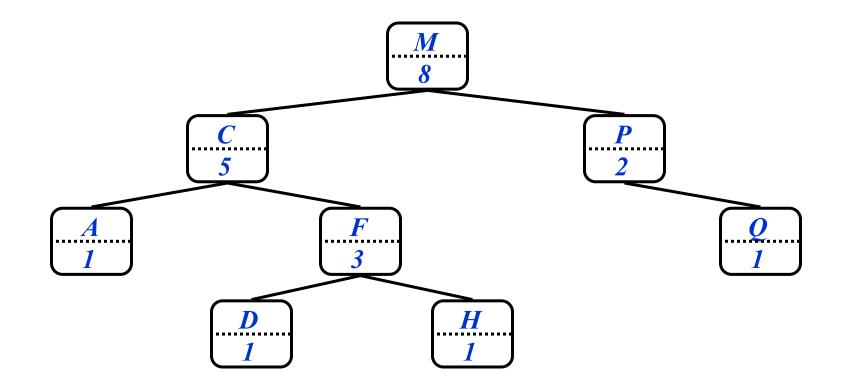
- We've seen algorithms for finding the *i*th element of an unordered set in O(*n*) time
- Next, a structure to support finding the *i*th element of a dynamic set in O(lg *n*) time
 - What operations do d namic sets usuall support?
 - What structure orks ell for these?
 - Ho could e use this str -0 (t) 0 (r)-0 (uc) 0255379 cm

Order Statistic Trees

- OS Trees augment red-black trees:
 - Associate a *si e* field with each node in the tree
 - x->size records the size of subtree rooted at x, including x itself:



Selection On OS Trees



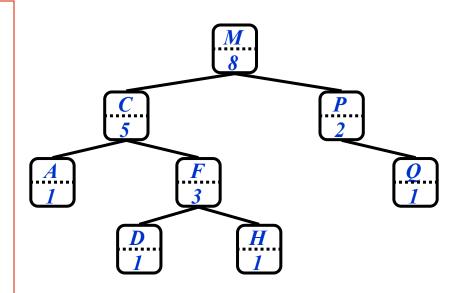
Ho can e use this propert to select the *i*th element of the set?

OS-Select

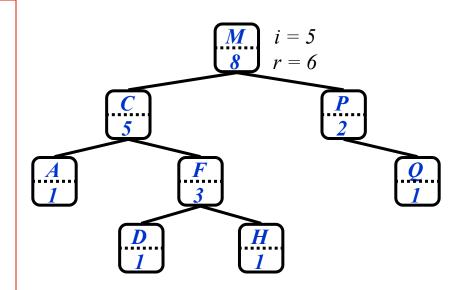
```
OS-Select(x, i)
{
    r = x - left - size + 1;
    if (i == r)
        return x;
    else if (i < r)
        return OS-Select(x->left, i);
    else
        return OS-Select(x->right, i-r);
```

}

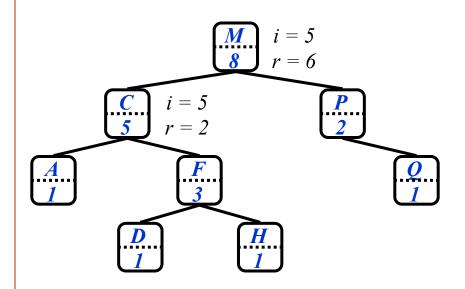
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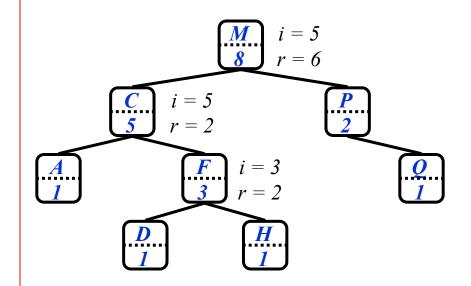
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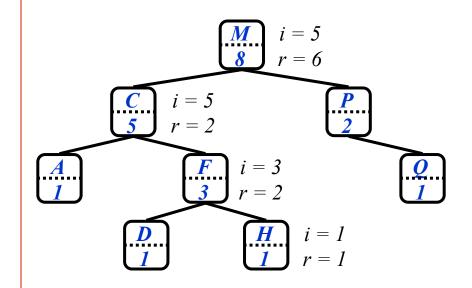
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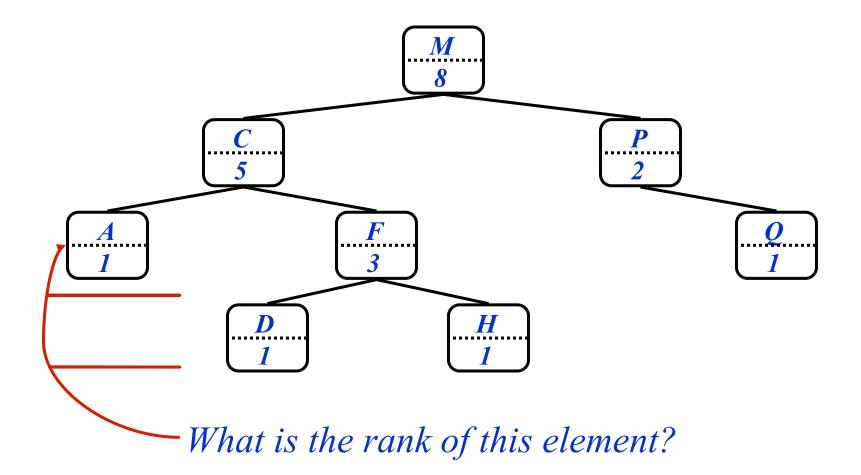


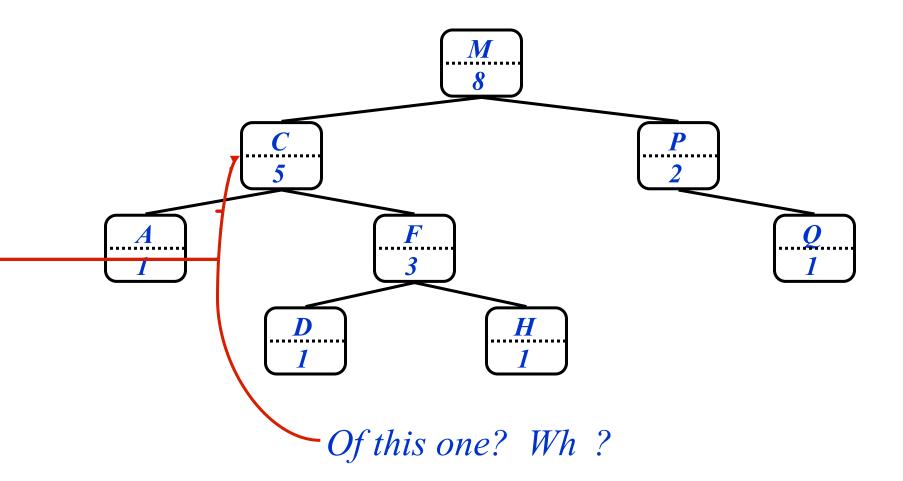
OS-Select: A Subtlety

```
OS-Select(x, i)
{
                                          Oops...
    r = x - left - size + 1;
    if (i == r)
        return x;
    else if (i < r)
        return OS-Select(x->left, i);
    else
        return OS-Select(x->right, i-r);
}
• What happens at the leaves?
• Ho can e deal elegantl ith this?
```

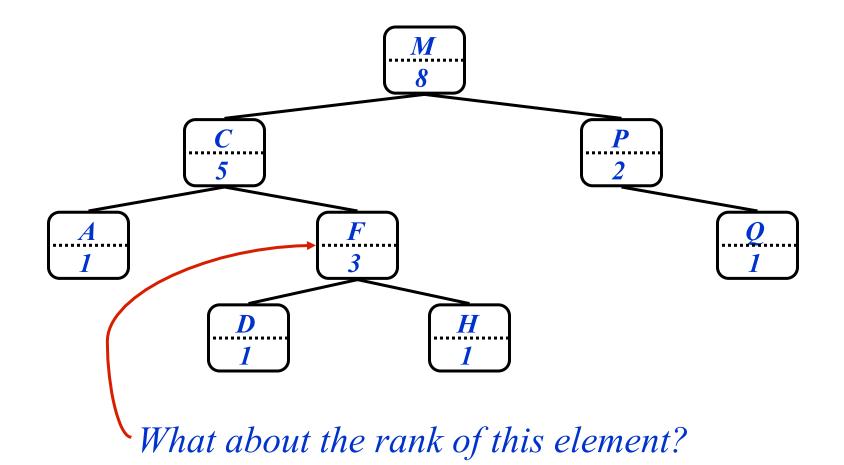
OS-Select

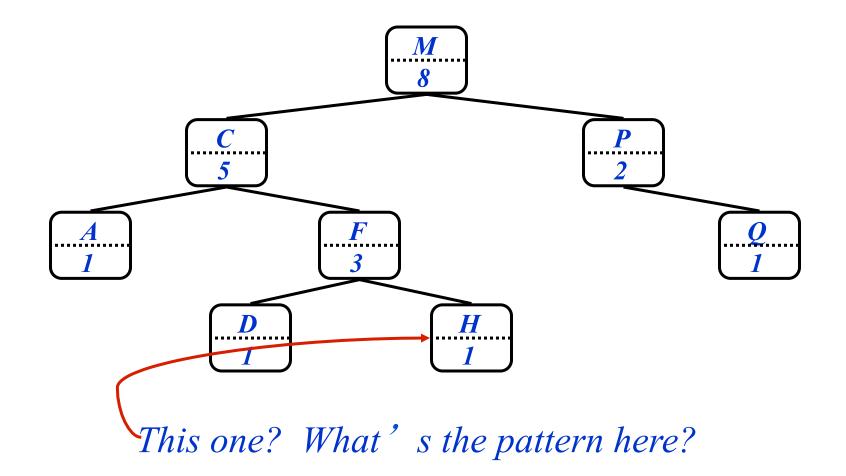
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        return OS-Select(x->right, i-r);
}
• What ill be the running time?
```





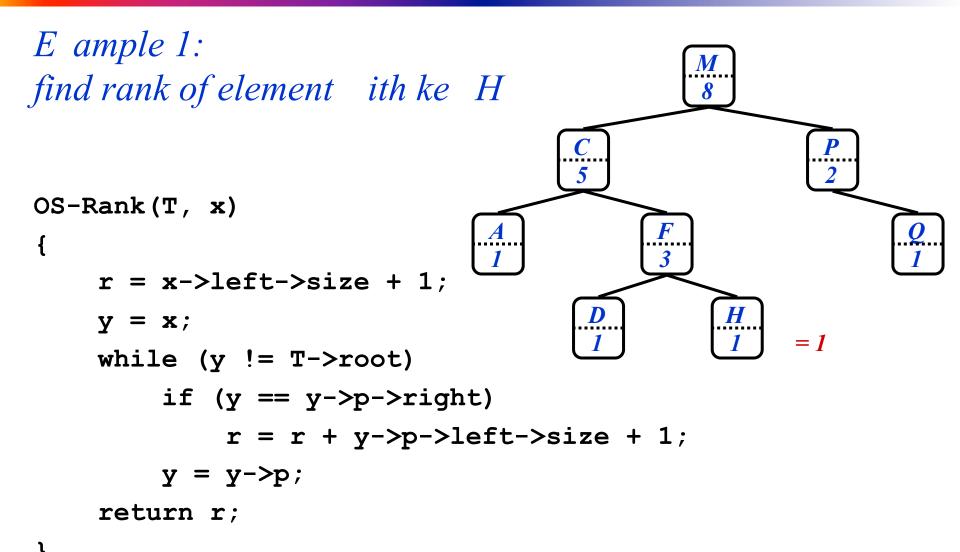


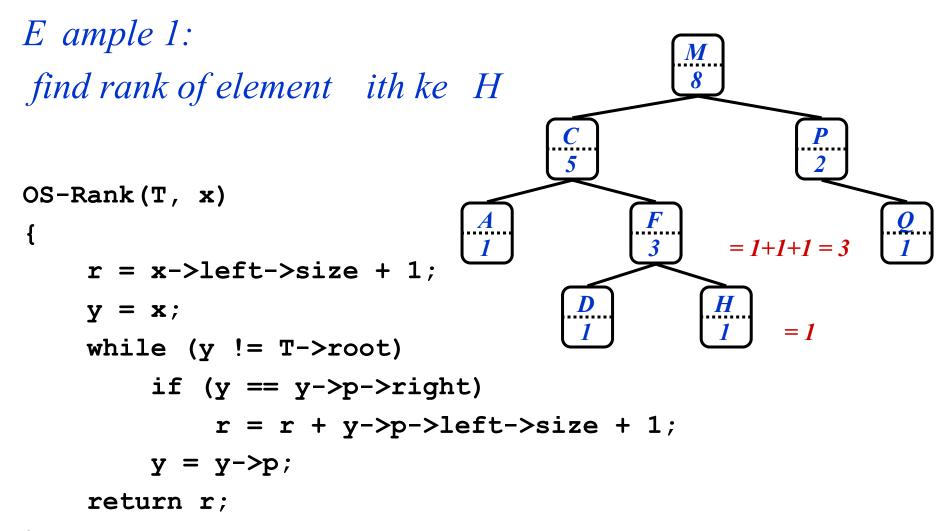


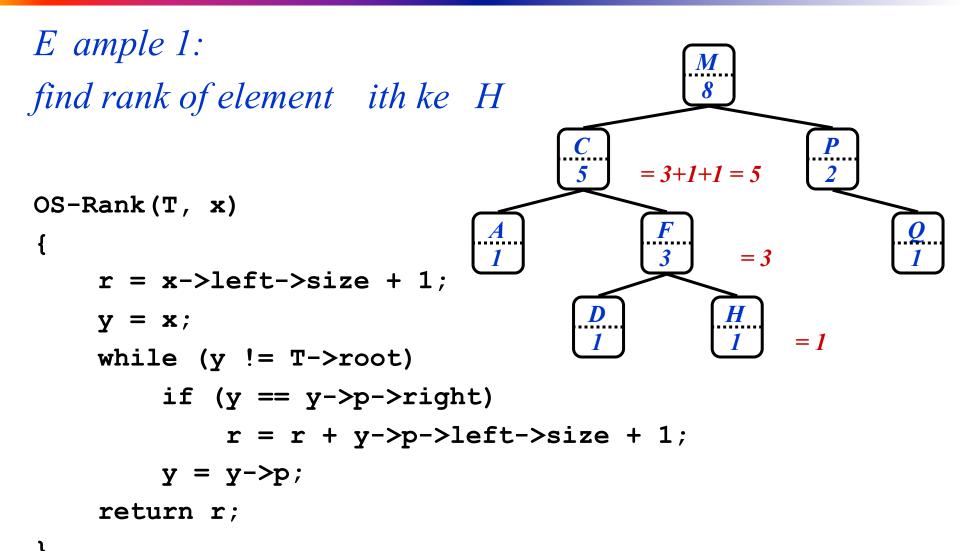


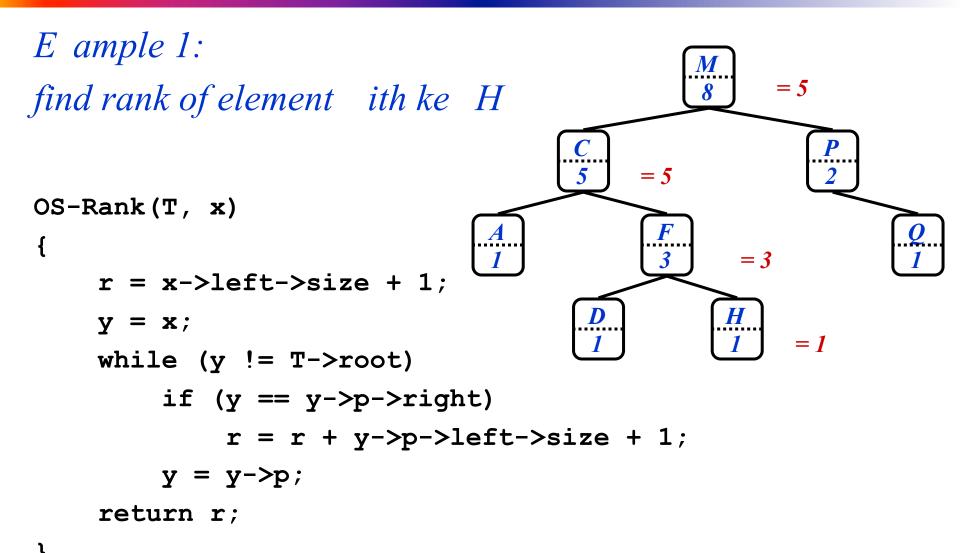
OS-Rank

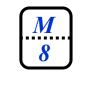
• What ill be the running time?



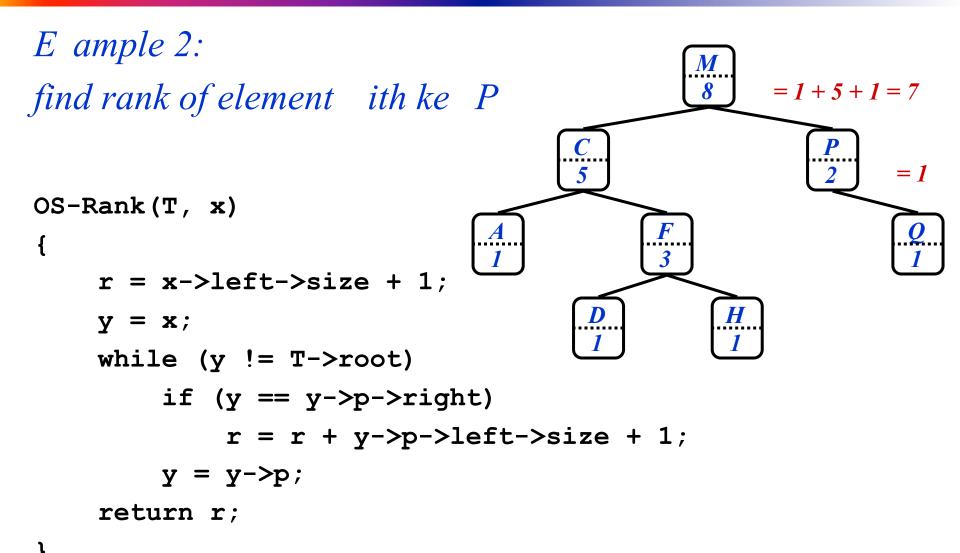








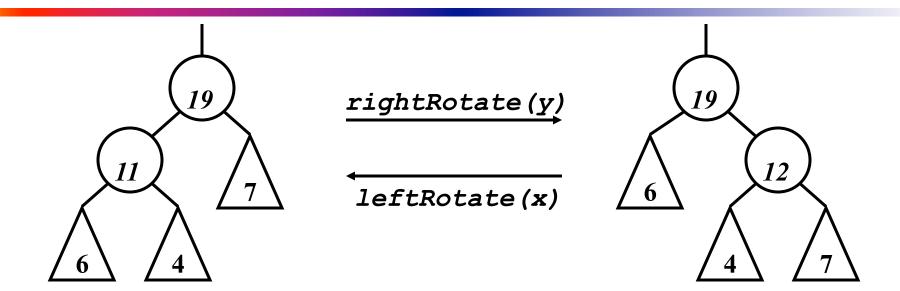




Maintaining Subtree Sizes

- So by keeping subtree sizes, order statistic operations can be done in O(lg n) time
- Maintain sizes during Insert() and Delete() operations
 - Insert(): Increment size fields of nodes traversed during search down the tree
 - Delete(): Decrement sizes along a path from the deleted node to the root
 - Both: Update sizes correctly during rotations

Maintaining Size Through Rotation



- Salient point: rotation invalidates only and
- Can recalculate their sizes in constant time
 Wh ?

Augmenting Data Structures: Methodology

- Choose underlying data structure
 - E.g., red-black trees
- Determine additional information to maintain
 - E.g., subtree sizes
- Verify that information can be maintained for operations that modify the structure
 - E.g., Insert(), Delete() (don't forget rotations!)
- Develop new operations
 - E.g., OS-Rank(), OS-Select()

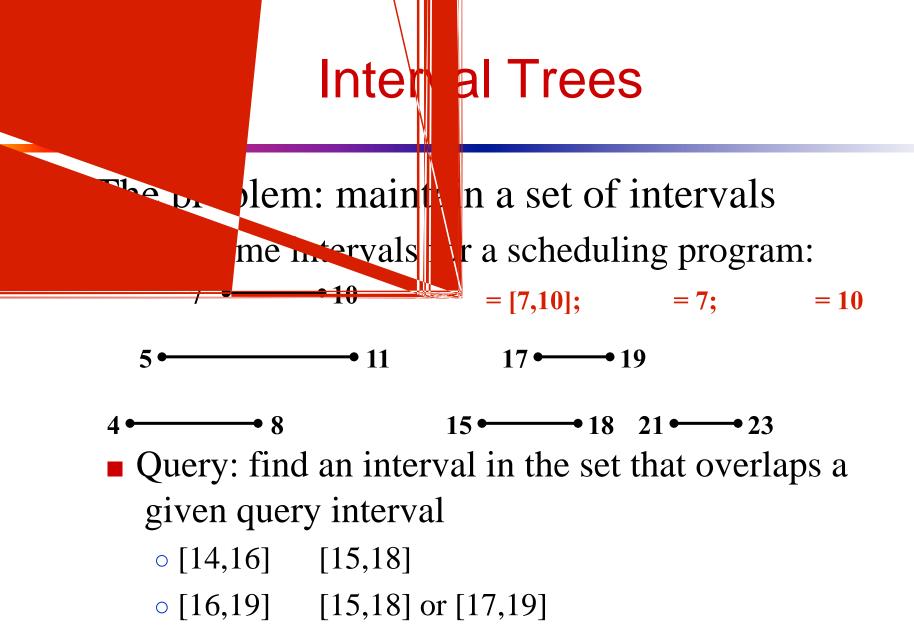
Advanced Data Structures

Augmenting Data Structures: Interval Trees

Review: Methodology For Augmenting Data Structures

- Choose underlying data structure
- Determine additional information to maintain
- Verify that information can be maintained for operations that modify the structure
- Develop new operations

- The problem: maintain a set of intervals
 - E.g., time intervals for a scheduling program:
 7 10



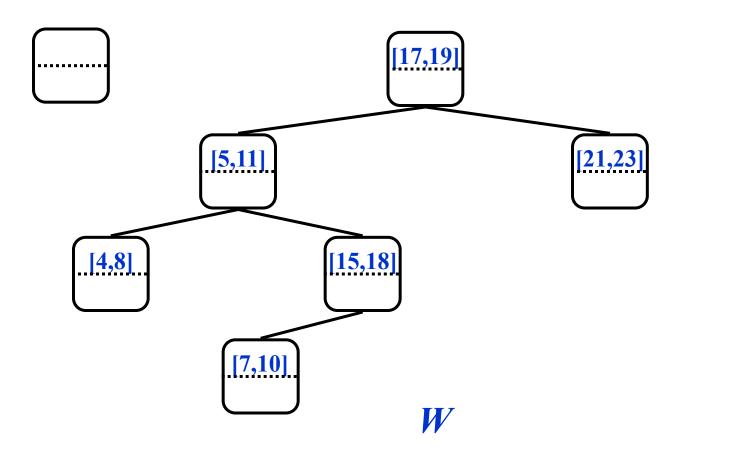
• [12,14] NULL

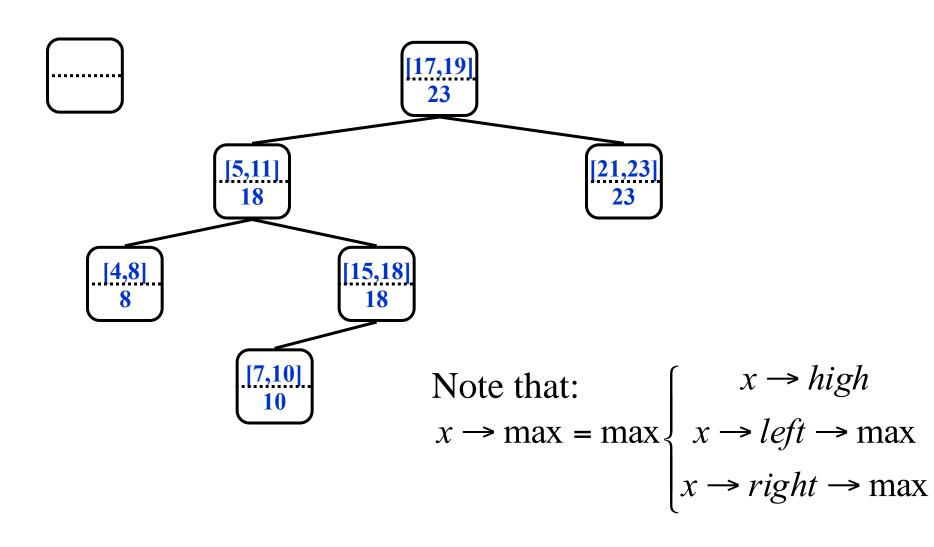
- Following the methodology:
 - Pick underlying data structure
 - Decide what additional information to store
 - Figure out how to maintain the information
 - Develop the desired new operations

- Following the methodology:
 - Pick underl ing data structure
 - Red-black trees will store intervals, keyed on *i* lo
 - Decide what additional information to store
 - Figure out how to maintain the information
 - Develop the desired new operations

- Following the methodology:
 - Pick underlying data structure
 - Red-black trees will store intervals, keyed on *i* lo
 - Decide hat additional information to store
 - We will store ma, the maximum endpoint in the subtree rooted at i
 - Figure out how to maintain the information
 - Develop the desired new operations

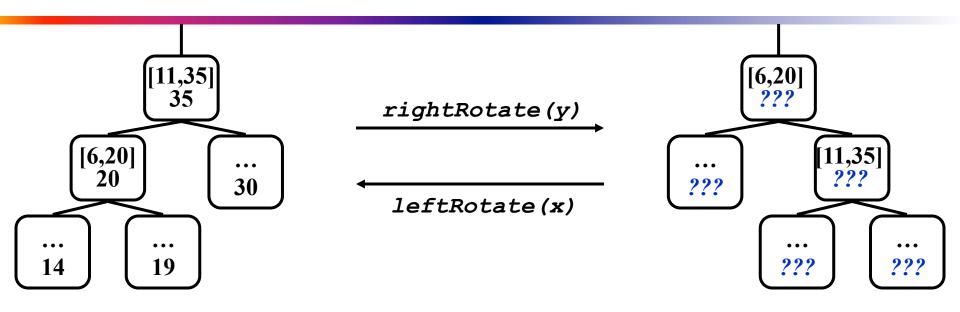
?



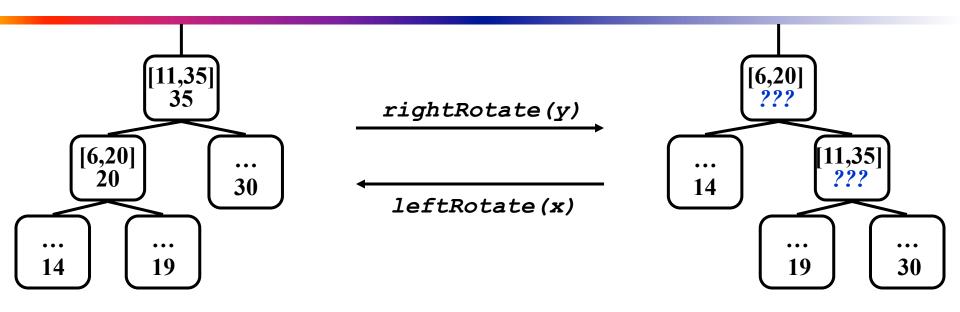


- Following the methodology:
 - Pick underlying data structure
 - Red-black trees will store intervals, keyed on *i* lo
 - Decide what additional information to store
 - \circ Store the maximum endpoint in the subtree rooted at i
 - Figure out ho to maintain the information

 Ho ould e maintain ma field for a BST?
 What's different?
 - Develop the desired new operations

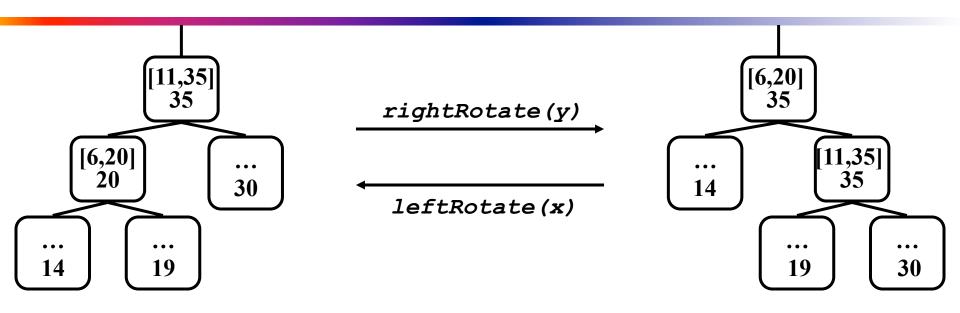


• What are the ne ma values for the subtrees?



• What are the ne ma values for the subtrees?

- A: Unchanged
- What are the ne ma values for and ?



• What are the ne ma values for the subtrees?

- A: Unchanged
- What are the ne ma values for and ?
- A: root value unchanged, recompute other

- Following the methodology:
 - Pick underlying data structure
 - Red-black trees will store intervals, keyed on *i* lo
 - Decide what additional information to store
 - \circ Store the maximum endpoint in the subtree rooted at *i*
 - Figure out how to maintain the information
 Insert: update max on way down, during rotations
 - Delete: similar

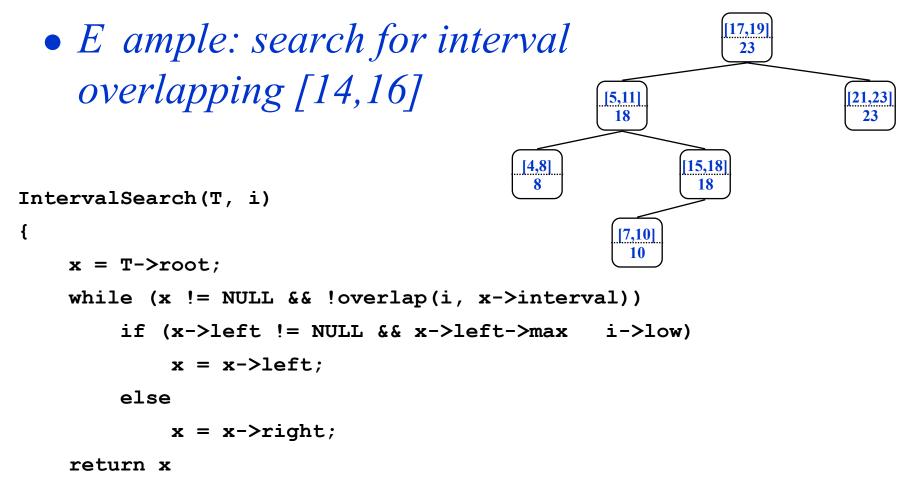
• Develop the desired ne operations

Searching Interval Trees

```
IntervalSearch(T, i)
{
    x = T - > root;
    while (x != NULL && !overlap(i, x->interval))
        if (x->left != NULL && x->left->max i->low)
            x = x - > left;
        else
            x = x - right;
    return x
}
```

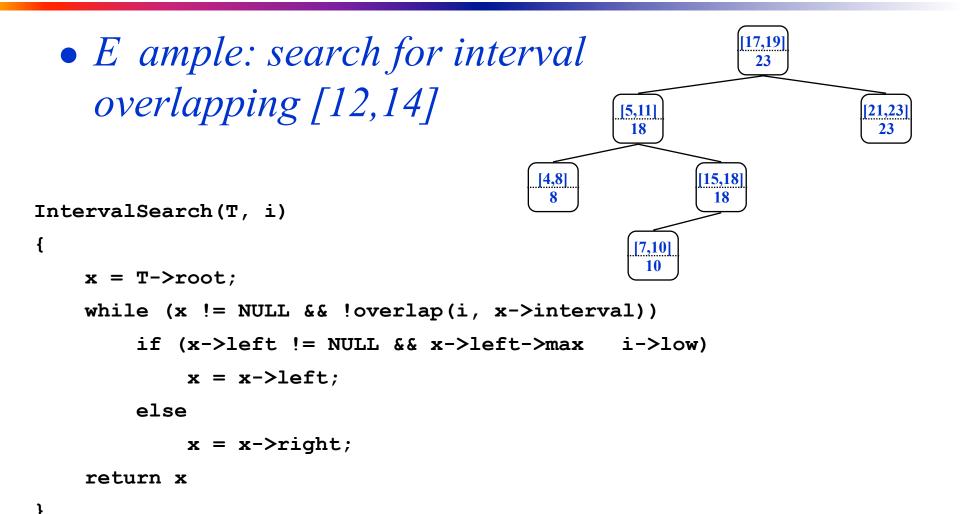
• What ill be the running time?

IntervalSearch() Example



}

IntervalSearch() Example



Correctness of IntervalSearch()

- Key idea: need to check only 1 of node's 2 children
 - Case 1: search goes right
 - \circ Show that \exists overlap in right subtree, or no overlap at all
 - Case 2: search goes left
 - \circ Show that \exists overlap in left subtree, or no overlap at all

Correctness of IntervalSearch()

- Case 1: if search goes right, \exists overlap in the right subtree or no overlap in either subtree
 - If ∃ overlap in right subtree, we're done
 - Otherwise:
 - x left = NULL, or x left max < i low (*Wh*?)

• Thus, no overlap in left subtree!

```
while (x != NULL && !overlap(i, x->interval))
    if (x->left != NULL && x->left->max i->low)
        x = x->left;
    else
        x = x->right;
    return x;
```

Correctness of IntervalSearch()

• Case 2: if search goes left, \exists overlap in the left subtree or no overlap in either subtree

■ If ∃ overlap in left subtree, we'